



Materials, Design & Manufacturing Facility (CWB) 材料、設計和製造中心(清水灣)

MDMF (CWB)

Introduction

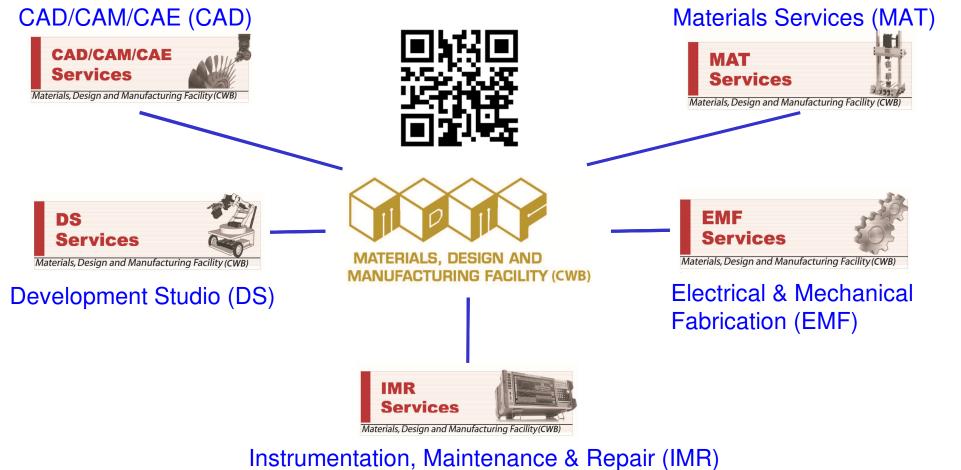
05/Mar/2024







Our Services – 5 Units



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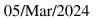






Services Scope – EMF

- Engineering design and fabrication supporting services
- Sophisticated mechanical & electrical parts/equipment for the university and industrial collaboration projects
 - Parts/equipment/controller is not available in market
 - Multidisciplinary and application oriented activities



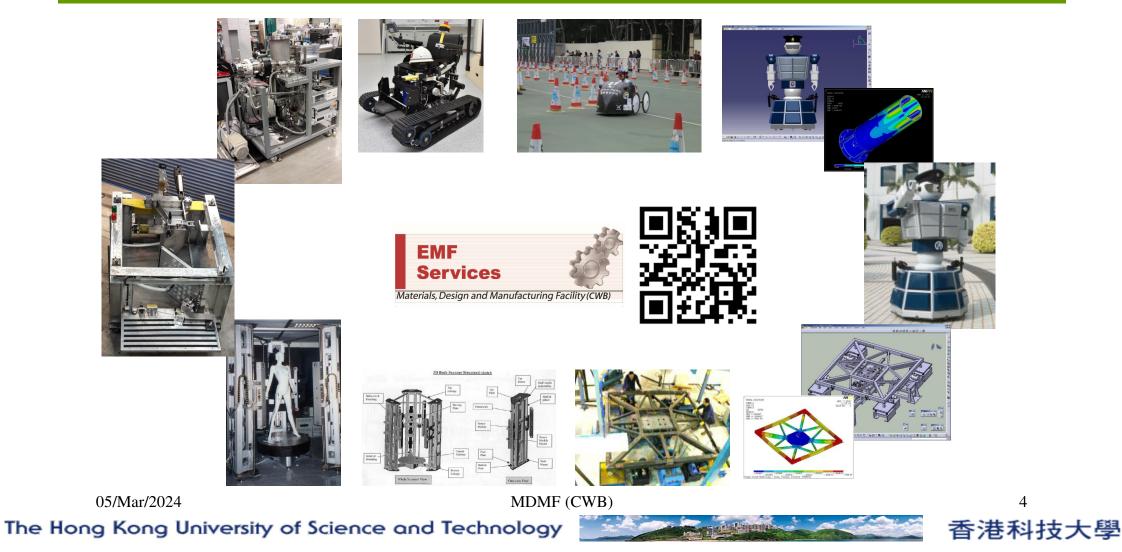
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Services Scope – EMF

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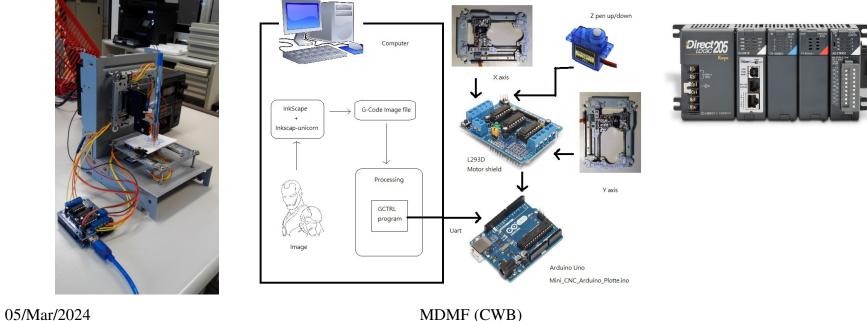




Services Scope – DS

• Controller design and fabrication supporting

- Controller boards, MCUs, cam, motors, sensors (environmental, motion, light, etc.)
- Eclipse for android development, Arduino IDE, Raspberry Pi, PLC
- PCB prototyping



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Services Scope - IMR

- Repair and maintenance of equipment
 - Scientific instruments, computer control machineries, laboratory equipment, and electrical safety
 - Especially for those which are no longer supported by the manufacturers
- Calibrations for multimeter, power meter, data logger, radiation monitor and temperature sensors





Services Scope - IMR

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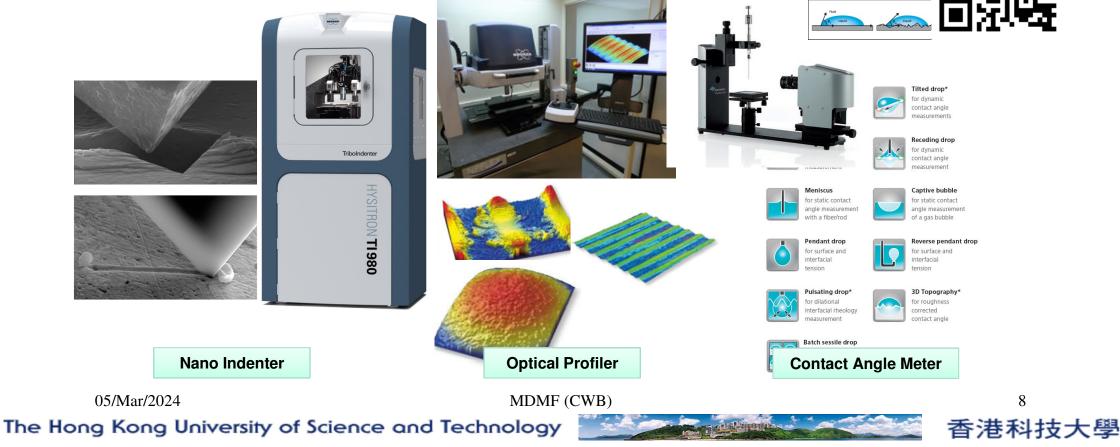






Services Scope - CAD

- Nano-measurement
 - Nano indenter, 3D surface metrology, optical profiler, contact angle meter

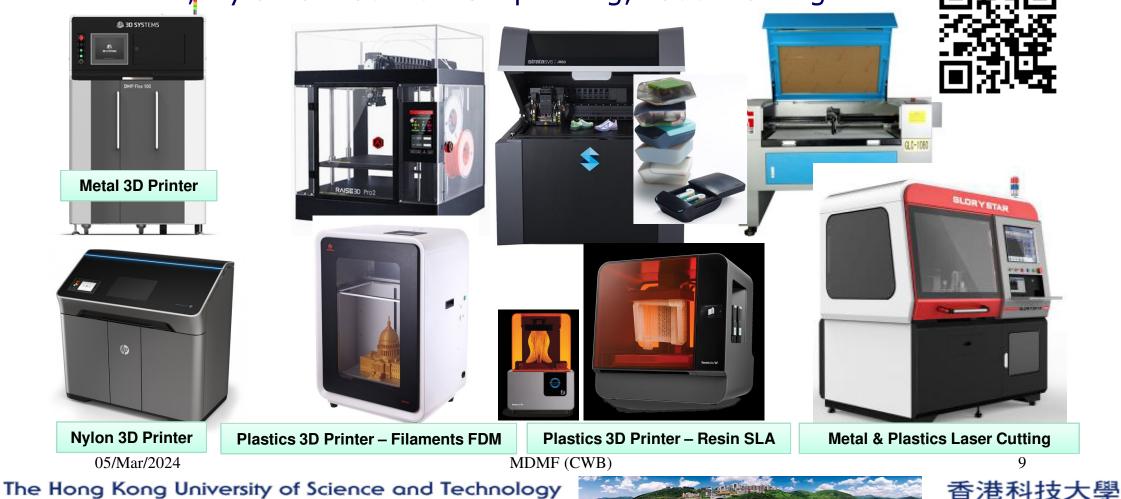






Services Scope - CAD

• Metal, Nylon & Plastics - 3D printing, Laser cutting







Services Scope - CAD

CAD/CAM/CAE system support, 5-axis metrology, 3D scanning, reverse engineering







- Mechanical Testing
 - also known as destructive testing, reveals the properties of a material under dynamic or static force



MTS 810 5KN to 100KN



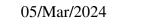
MTS 858 15kN Axial and 100 Nm Torsion

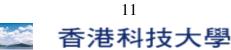
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MTS 858 Mini Bionix 25KN Axial, 250 Nm Torsional









- Inspection and Failure Analysis
 - determining the root cause of parts/assembly failure and working out the means for correcting and preventing current/future problems

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X Ray with CT imaging inspection system:

yxlon Cougar EVO

Detail Detectability : < 0.75µm

Spatial Resolution : 1.5µm

Max. Object Size : 440mm x 540mm



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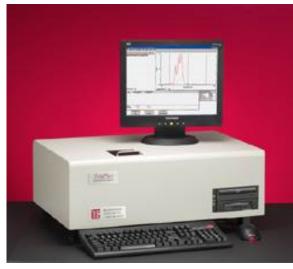
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- Inspection and Failure Analysis
 - determining the root cause of parts/assembly failure and working out the means for correcting and preventing current/future problems



Zeta Potential / Nano-particle Analyzer: ZetaPlus Zeta Potential Range : -150 to + 150 mV Size Range : 10nm to30µm



TecScan 7 Axis Immersion Scanner 1600mm x 800mm x 800mm sample length





C-SAM: Sonix Quantum 350H Spatial resolution:0.5 μm Depth resolution: 8 μm

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- **Inspection and Failure Analysis**
 - determining the root cause of parts/assembly failure and working out the means for correcting and preventing current/future problems



Particle Size Analyzer Measurement capability from 0.01 to 2800 microns



Microscope: Topcon TMM-13OZ Measuring range: 130 x 130 x 50 mm Minimum indication: 0.001 mm Accuracy: (3 + 2.5L/100) μm

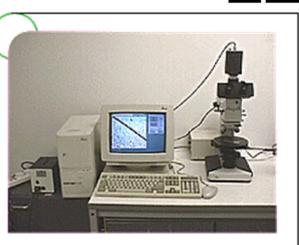
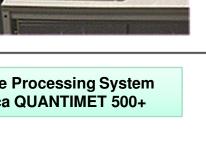


Image Processing System Leica QUANTIMET 500+

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- Sample Processing
 - processing of metal heat treatment, polymer and carbon composite



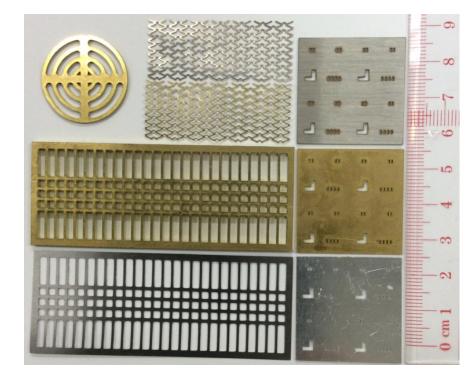
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Project – Metal Laser Cutting

• Fiber laser cutting machine of 1.5kW

- Working area: 630 x 530 x 90 mm
- 4th rotary axis for round pipe cutting









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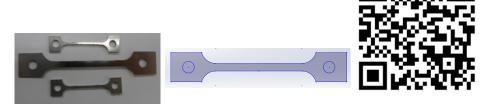


Project – Metal Laser Cutting

• Examples

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- SMA specimens
 - Tensile specimen:
 - Materials / Thickness: 1mm
 - Production time: 45 second
 - Crack specimen:
 - Materials / Thickness: 1.5mm
 - Production time:1 min.





- S.S. Filter specimen
 - Materials / Thickness: 1.2mm
 - Production time:8min. 30 second
- Ti Electrode specimen
 - Materials / Thickness: 1mm
 - Production time: 2min.















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Project – Laser Marking & Engraving

- Laser Marking Machine
 - 10W fiber laser
 - Max. size is 110mm X 110mm





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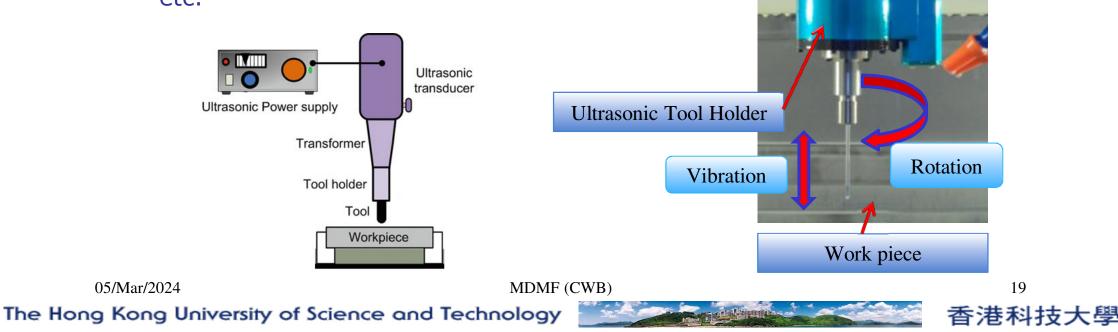
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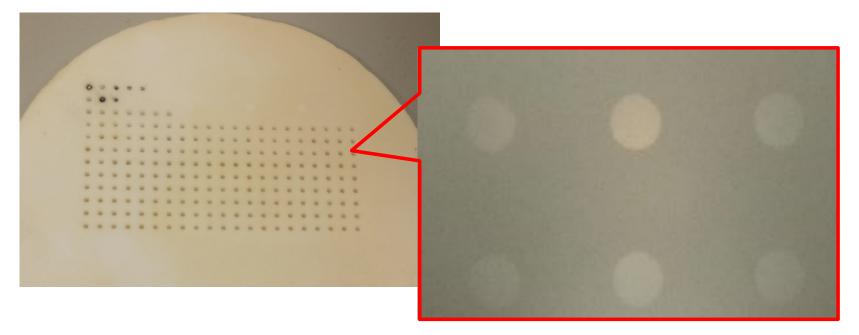
- Ultrasonic tool holder
 - Fast, small and deep hole machining
 - Length / Diameter > 10
 - Hard or ultra-hard material cutting
 - Glass, Ceramics, Vulcanization silicon, etc.
 - Stainless steel, Tungsten steel, Molybdenum, etc.







- Examples
 - Alumina, Small hole drilling / milling (blind hole)
 - Hole diameter = 1.2mm; depth = 1.4mm
 - # of holes to be drilled per workpiece = 400





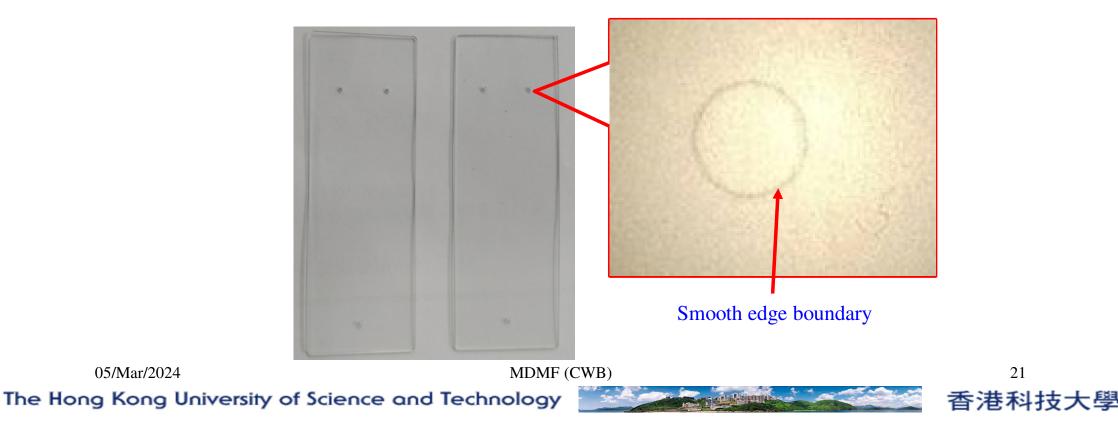




Examples

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- Glass, Small hole drilling (thru' hole)
 - Hole diameter = 0.6mm; Glass plate thickness = 1mm
 - # of holes to be drilled per workpiece = 4 •



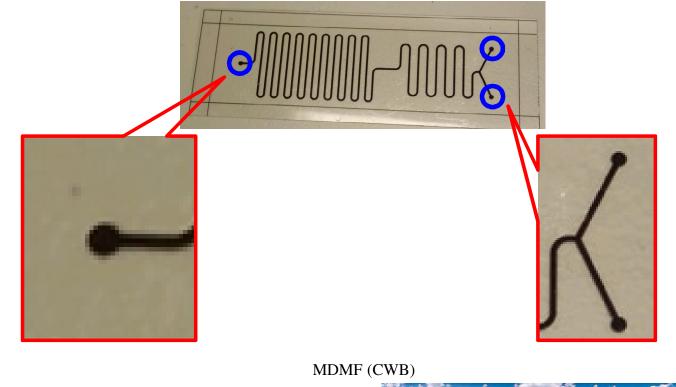


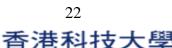


• Examples

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- Glass channel, Small hole drilling (thru' hole)
 - Hole diameter = 1.0mm; depth = 1mm
 - # of holes to be drilled per workpiece = 3



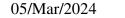






- Examples
 - Stainless steel, Small hole drilling (blind hole) —
 - Hole diameter = 0.2mm and 0.9mm
 - Depth = 5mm and 20mm
 - SMA Shape Memory Alloy, Small hole drilling _ (thru' hole)
 - Hole diameter = 0.075m
 - Thickness = 2mm



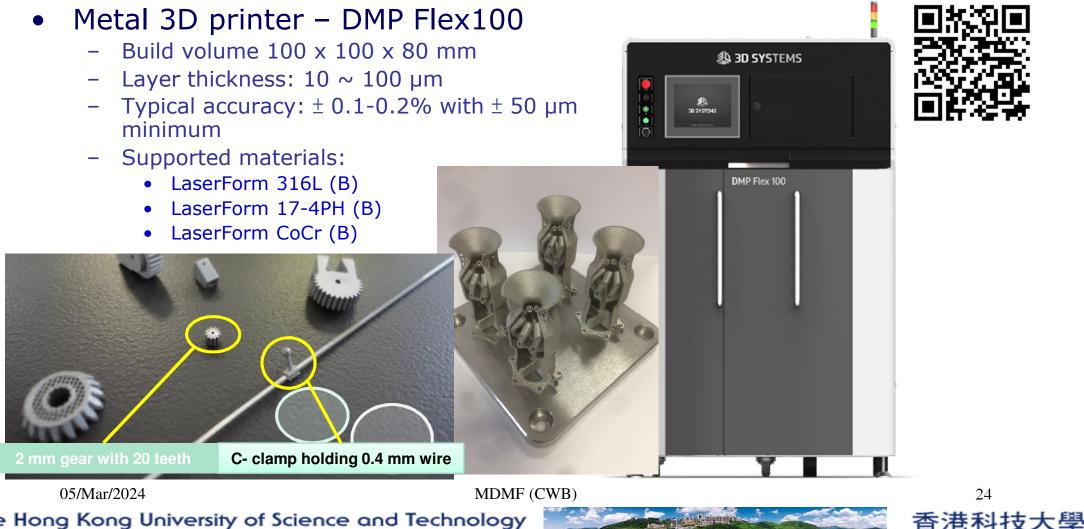


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Project – Metal 3d Printing

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Project – Nylon 3d Printing

• Nylon 3D printer – HP Jet Fusion 540

- Build volume 332 x 190 x 248 mm
- Layer thickness: 0.08 mm
- Typical accuracy: ± 0.3% with ± 0.2 mm minimum
- Supported materials:
 - Nylon PA12

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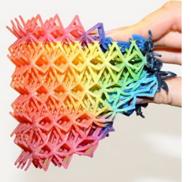




Project – Industrial SLA 3d Printing

• Industrial SLA 3D printer – J850 PRIME

- Build volume 490 x 390 x 200 mm
- Layer Thickness : down to 14 µm
- File Formats for Printing :
 - Color and Texture: 3MF / OBJ / SolidWorks / VRML
 - Color: CATIA / Creo / Inventor / IGES / JT / Parasolid / NX / SolidEdge / STEP
 - None: STL
- Accuracy :
 - Under 100 mm ±100µ
 - Above 100 mm $\pm 200 \mu$ or \pm 0.06% of part length, whichever is greater
- Digital model materials: Unlimited number of composite materials including:
 - Over 600,000 colors with VeroUltra
 - Rubber-like materials in a variety of Shore A values
 - Translucent color tints



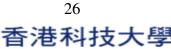




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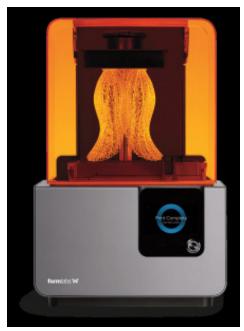






• Desktop SLA 3D printer – Form 2

- Build volume 145 x 145 x 175 mm
- Layer Thickness 0.025 0.1 mm
- File Formats for Printing: STL, OBJ
- Professional print quality









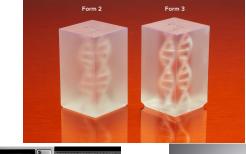






• Desktop SLA 3D printer – Form 3L

- Build volume 335 x 200 x 300 mm
- Layer Thickness 0.025 0.3 mm
- File Formats for Printing: STL, OBJ
- Low Force Stereolithography (LFS)[™]





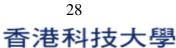






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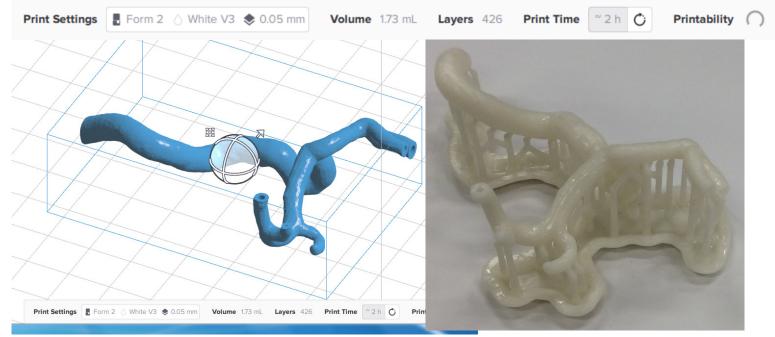








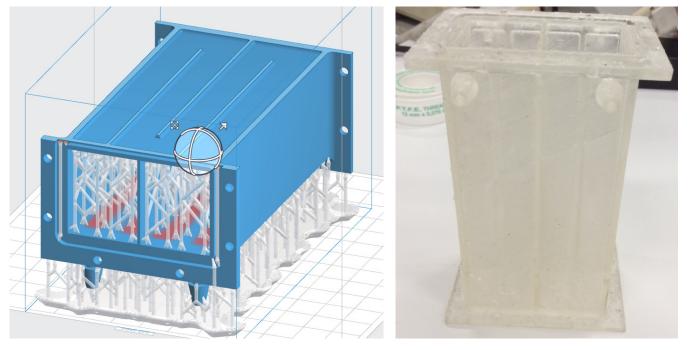
- Examples
 - Blood vessel
 - Materials Standard White
 - Minimum feature size = 0.5mm







- Water channel model
 - Materials Standard Clear
 - Channel size = 2.5mm
 - Internal water circulation



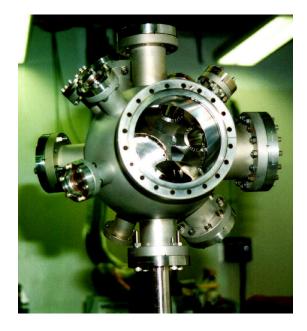


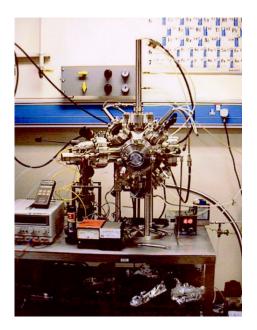




Project – High Vacuum Chamber

- High vacuum stainless steel chamber
 - Design and build an enhanced HVC with tailor made functionalities
 - Vacuum level less than 10⁻⁸ torr





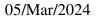




Project – Reactive Ion Etcher

- Design and build the reactive ion etcher in wafer fabrication
 - Tailor made functionalities





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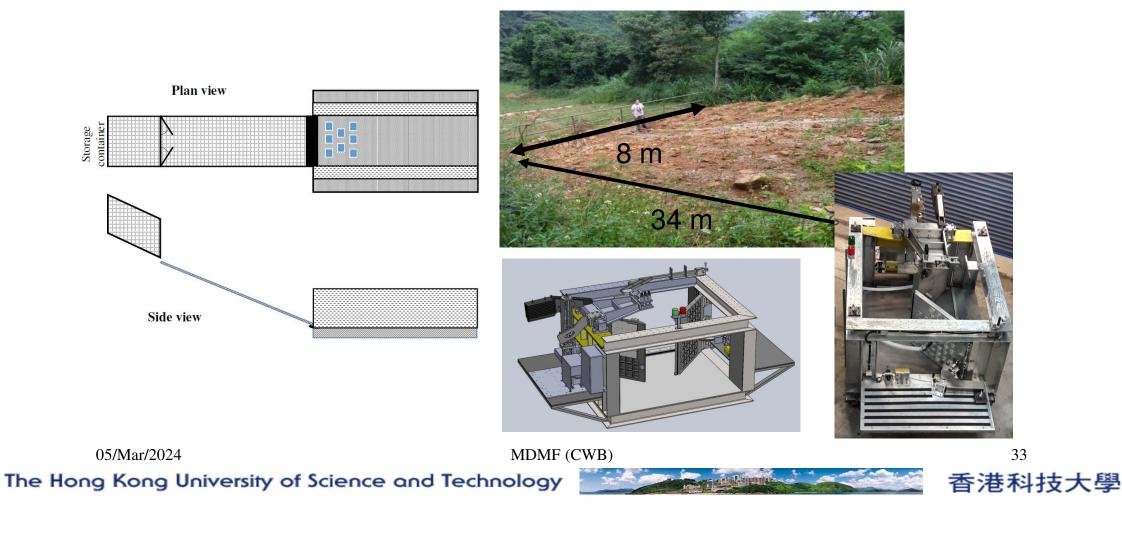






Project – Soil Retaining Gate

• Design and build the soil retaining gate of a flume model







Project – Shaking Platform

- Design and build the shaking platform for
 - Active vibration control of earthquake / wind excited structures
 - Assessment of motion acceptance criteria for human occupancy in the design of flexible structures



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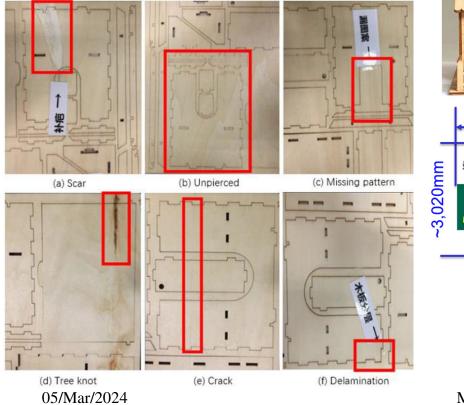
Project – Automatic Flaws Inspection System

 To automate the detection process of natural and manufacturing flaws before/after laser cutting a plywood board.

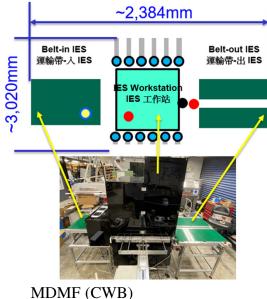


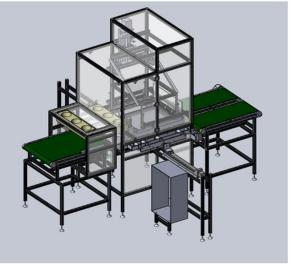
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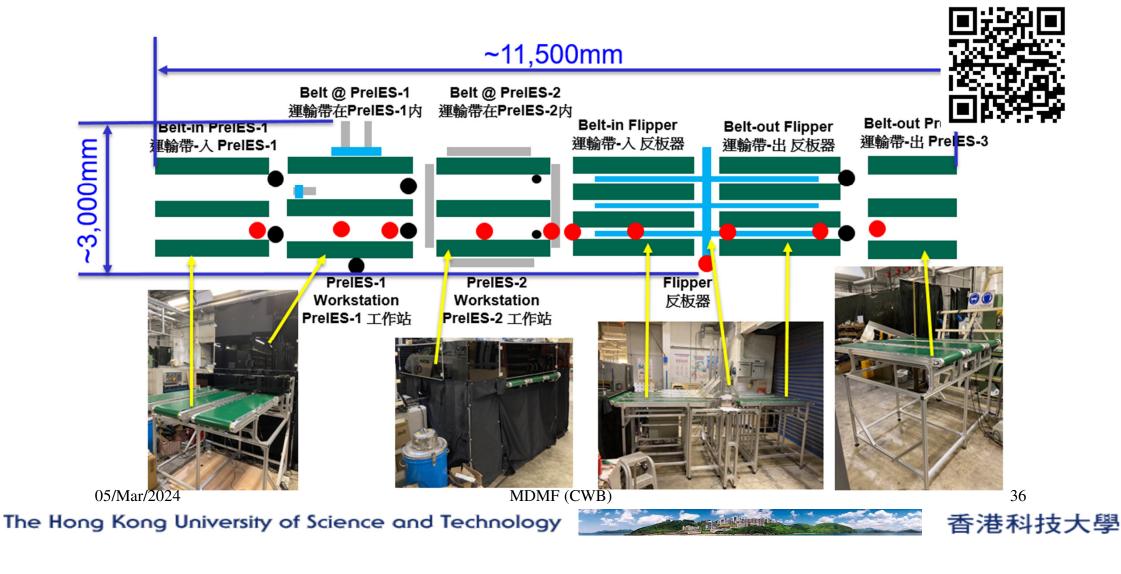








Project – Automatic Flaws Inspection System







Project – CIPP Repair Robot Cutter

• To develop an automatic robot cutter that can cut the lateral connection branch opening during underground drainage pipe repairing in Hong Kong.

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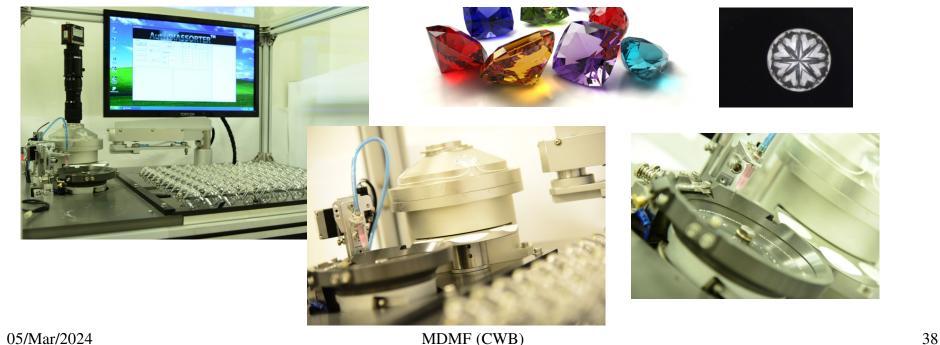




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Project – Diamond Sorter

- An automation system to sort gems into different size / color / shape / transparency grades and to measure the cutting / cracks on diamonds
 - Involves the R&D of a vision system, image processing module and an electromechanical mechanism



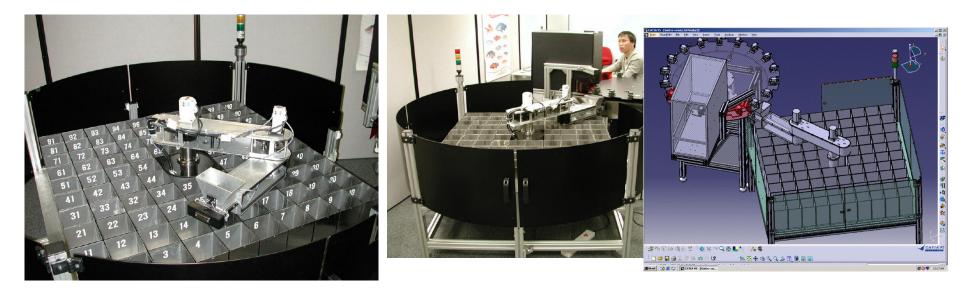




Project – Feather Sorter

- To sort feathers of different features for the shuttlecock manufacturing industry.
 - Involves the R&D of a turning table, an image processing system and a robotic arm, which selects feather into the bin matrix according to their degree of curvature











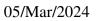
Project – Controller for Embroidery Machine

- Design and develop a controller to control the embroidery machine more precisely and at higher speed, with less vibration
 - Linux in an embedded system, with advanced control algorithms for accurate positioning, tension control, automatic compensation

of vibration



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Engineering / Robotic Design Competition

- RoboCon
- ROV
- Cybathlon
- Pedal Kart
- Power Bike











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